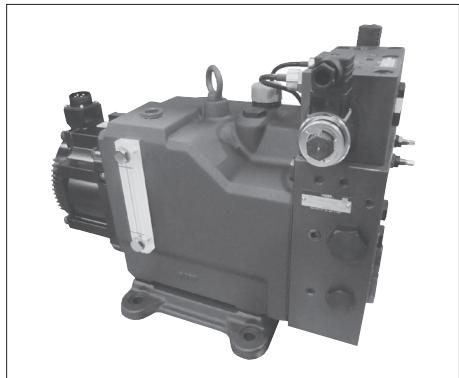


Intelligent Hydraulic Servo Drive Pack

The IH (intelligent hydraulic) servo drive pack is a compact energy-saving and low-noise hydraulic device which is combined as one with the AC servo motor, bidirectional rotation piston pump, reservoir and hydraulic control circuit. This combination can control the number of revolutions of the servo motor and adjust the discharge and pressure of the pump. This device can be combined with the sensor – equipped cylinder and dedicated controller to facilitate the configuration of a position, speed and pressure control system.



● Energy Saving

The operation at the number of revolutions meeting the machine requirements (flow rate and pressure) reduces useless power losses and provides energy savings.

Furthermore, by using bidirectional rotation pump, need no directional control valves, so can minimize pressure loss.

● Low Noise

During pressure control, the pump rotation compensating for the internal leakage of oil pressure provides low revolutions with almost no noise. During flow control, the number of revolutions meeting the machine requirements ensures lower noise generation than conventional devices.

● Compact

A substantial reduction in heat generation enables the operation with a minimum amount of fluid oil for cylinder operation in addition something extra oil. This results in a combination of the servo motor, piston pump, reservoir and hydraulic control circuit in one, providing energy savings. Incorporation into an integral part of the machine is also possible.

● Digital Control

Software control of the dedicated controller allows a system to have a great deal of versatility.

Digital control parameter setting facilitates to operate the system and its maintenance, furthermore the analog input/output ports provide as standard for user interface.

● Optional Circuit Support

As for the option of tare load circuit, it is possible to built-in counterbalance valve and shut-off valve. (only for YSD2 type and YSD3 type)

■ Specifications

Model Numbers	Geometric Displacement of Pump cm ³ /rev	Max. Rotational Speed r/min	Thrust Output and Cylinder Bore	Reservoir Capacity cm ³	Oil Level Variations cm ³
YSD1-* -09/13	6, 10	2000*	20 - 30 kN (Cylinder Bore 63)	2500	1500
YSD2-* -24/29/44	6, 10, 16		50 - 60 kN (Cylinder Bore 80)	4200	2500
YSD3-* -55/75	10, 16, 30		100 kN (Cylinder Bore 100)	5800	3500

*There are cases when the max. rotational speed is limited by operating pressure and motor output.

■ Instructions

● Transportation

Use the hanging hook embedded with this pack for transportation. Don't hang a kind of wires for lifting at the place except for that of hanging hook.

● Piping

When use steel pipes, please be careful not to apply excessive force by piping on this pack.

● Oil Supply

The oil gauge is embedded with this pack. Before operation, please supply specified hydraulic fluid oil from reservoir filling port to the standard level of oil gauge.

● First Operation

At the first operation after installation, start-up with the pressure signal set near by unload pressure and confirm the fluid suctioned normally.

● Air Vent

The air mixing inside the equipment or pipe may occur some vibrations, so please vent air completely.

As of YSD2/YSD3 type, air vent valves embedded on two places of rod side and head side, please operate under the condition that the applicable ports of each air vent valve are set on discharge side.(Never operate under the condition set on suction side.)

● In Operation

In operation, the temperatures of AC servo motor and body surface are high, so please prevent hands or body from touching the pack.

● Area Difference between Cap Side and Rod Side of Cylinder

If the area difference between cap side and rod side of cylinder is small, please contact us separately.

■ Exchange Period of Hydraulic Fluid

After first operation, please exchange the hydraulic fluid after three months or operating 500 hours later. After the first exchange, please exchange about every two years or total 5000 hours operation, whichever is earlier.

If the contamination level or characteristic of hydraulic fluid is outside of specified values, please exchange the hydraulic fluid regardless of the period above.

K

IH Servo Drive Pack

■ Model Number Designation

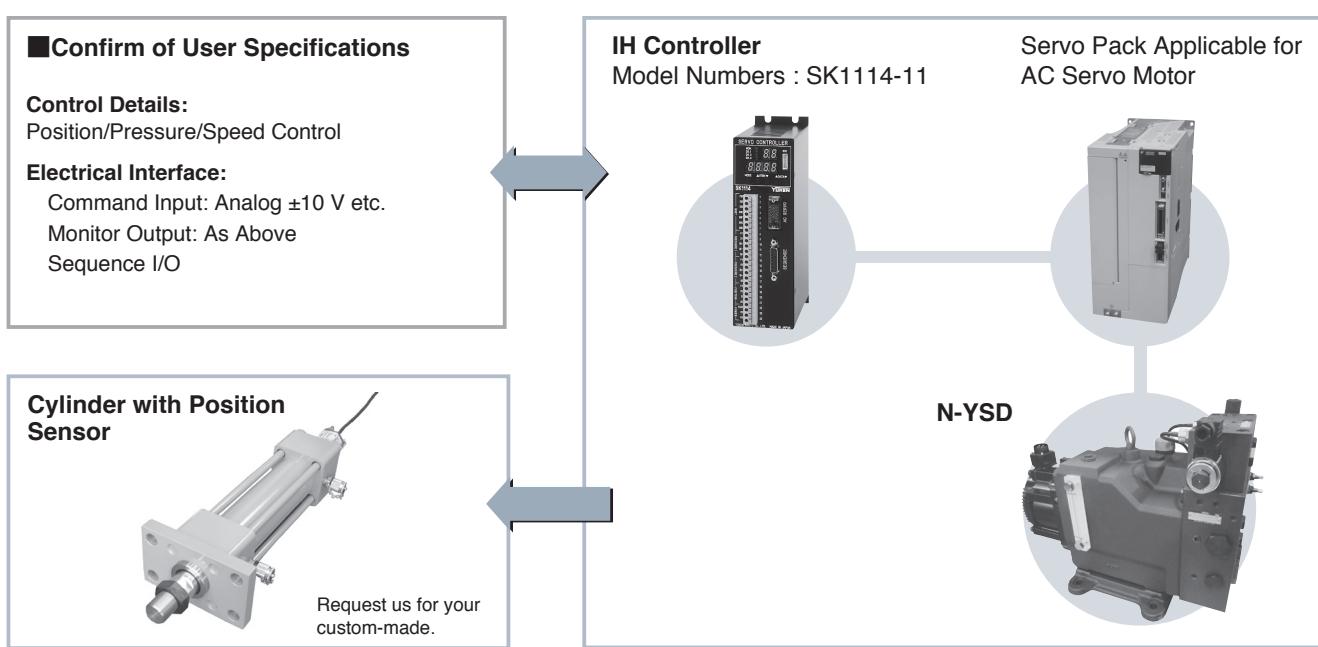
N-	YSD3	-F	-55	A	55 ^{*1}	-10	-H	R	-B	A ^{*2}	B ^{*2}	R	-30
Sub Ass'y Code	Series Number	Mtg. Type	Servo Motor Output kW	Direction of servo Motor Connection (Viewed from the Motor End)	Servo Pack kW	Geometric Displacement of Pump cm ³ /rev	Relief Valve Setting Pres. MPa	Pressure Sensor	Counterbalance Valve	Option Related			
										Pres. Adj. Range of Head Side Counterbalance Valve MPa	Pres. Adj. Range of Rod Side Counterbalance Valve MPa	Shut-off Valve	Design Number
N : Pump Motor Sub Ass'y (Omit if not required)	YSD1	F : Flange Mtg. Type	N1 : Without Servo Motor (For 0.85kW) N2 : Without Servo Motor (For 1.3kW)	A : Upward B : Downward	N : None 09 : 0.85 13 : 1.3	6 : 6 10 : 10 13 : 1.3	B : 9.5 C : 18.5	H : Head Side R : Rod Side	— — —	— — —	— — —	— — —	20
	YSD2	B : Blacket Mtg. Type	N : Without Servo Motor 24 : 2.4 29 : 2.9 44 : 4.4	R : Right L : Left	N : None R : Right 24 : 2.4 29 : 2.9 44 : 4.4	6 : 6 10 : 10 16 : 16	B : Both Side N : Without Pressure Sensor C : 18.5	H : Head Side R : Rod Side B : Both Side None : Without Counterbalance Valve	H : Head Side R : Rod Side B : Both Side None : Without Counterbalance Valve	B : ★ ³ - 7	H : Head Side R : Rod Side B : Both Side None : Without Shut-off Valve	H : Head Side R : Rod Side B : Both Side None : Without Shut-off Valve	30
	YSD3		N : Without Servo Motor 55 : 5.5 75 : 7.5		N : None 55 : 5.5 75 : 7.5	10 : 10 16 : 16 30 : 30	H : 23.5						

★1. If pump motor sub ass'y is selected, no need to fill in this item (Not selectable).

★2. If select those of without counterbalance valves, this item is none.

★3. Please refer to the "Minimum Adj. Pres. Characteristics"(Pages K-66 and K-67).

■ System Configuration

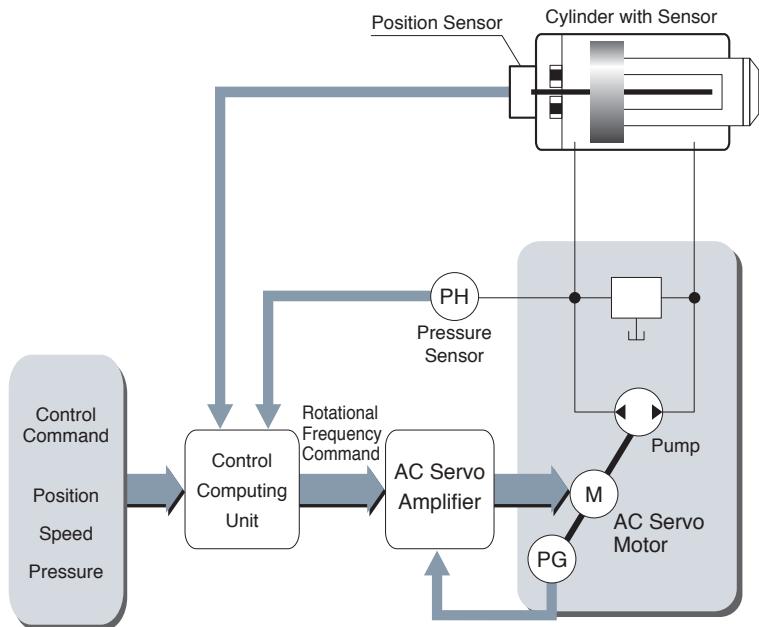


Note) Model number 《YSD *》 does not include IH Controller: SK1114-11 and Cylinder with Position Sensor.

If use those equipments, please order separately.

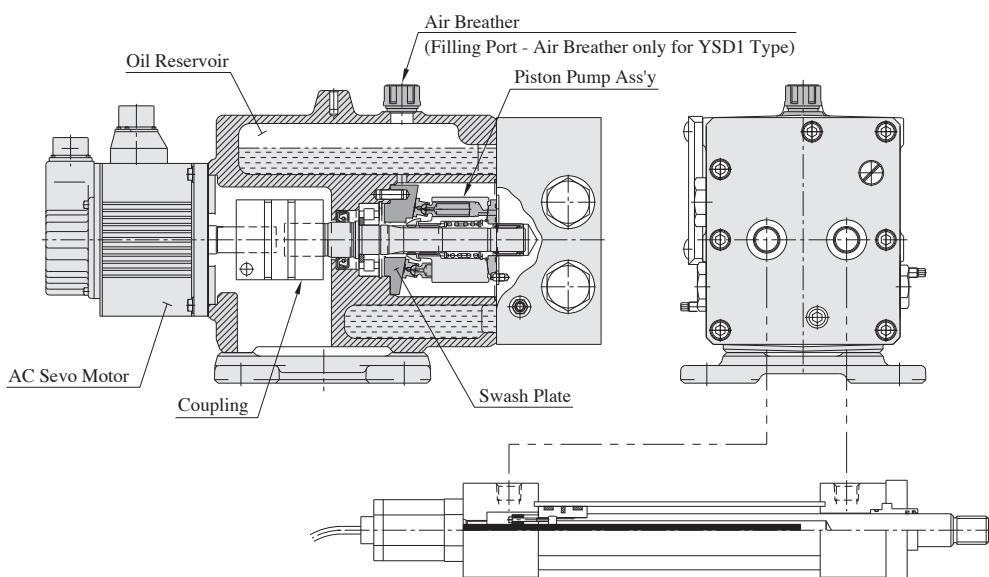
■ Operation

The bidirectional revolution piston pump is driven by AC servo motor and supply pressured oil to normal or reverse directions. So this is a simple hydraulic circuit only to connect the load cylinder on both output ports. The fluid suction of pump is operated by supplying from cylinder back line and compensation by self-suction valve for excess/ efficiency of oil quantity. As of control, provide the control deviation output between upper signal and sensor signal to servo driver (AC servo amplifier), and construct the feedback loop by driving AC servo motor.

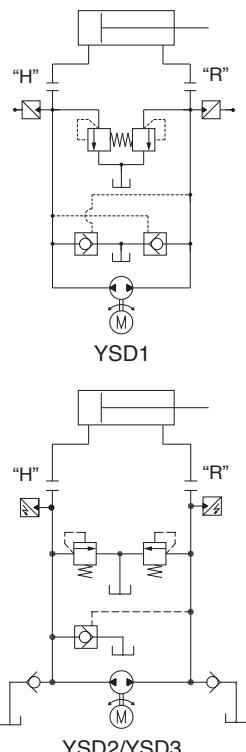


■ Structure / Hydraulic Circuit

The IH servo drive pack pump is a bidirectional revolution piston pump which offers high performance in a wide range of very low to high revolution. The hydraulic control circuit simply consists of safety valves and self priming valve, without a control valve in the pump discharge line and the series line between cylinders. The reservoir is made compact by using space around the pump. With the oil supply port of hydraulic fluid doubling as an air breather and the side-mounted oil level gauge, the pump is well equipped as a hydraulic driving force.



Hydraulic Circuit



● Energy Saving Hydraulic System by Rotational Frequency Control

Energy saving on hydraulic control is achieved by sensing load pressure and control to avoid excess fluid discharge for the required (Output) = (Pressure) \times (Flow). Piston pump generally discharge required flow by changing swash plate degree and control geometric displacement.

On the other hand, the rotational frequency control achieves by control rotational speed of motor. That is, (Flow) = (Rotational Speed) \times (Geometric Displacement of Pump). In this case, sensing load pressure by pressure sensor and construct energy saving system by electric feedback control.

As the conventional way with the pump of high speed fixed rotation, there are some power losses from internal hydraulic drain and low efficiency of induction motor at low load operation. As the rotational frequency control system, the motor rotate on requirement and supply flow, so that is excellent as for energy saving system.

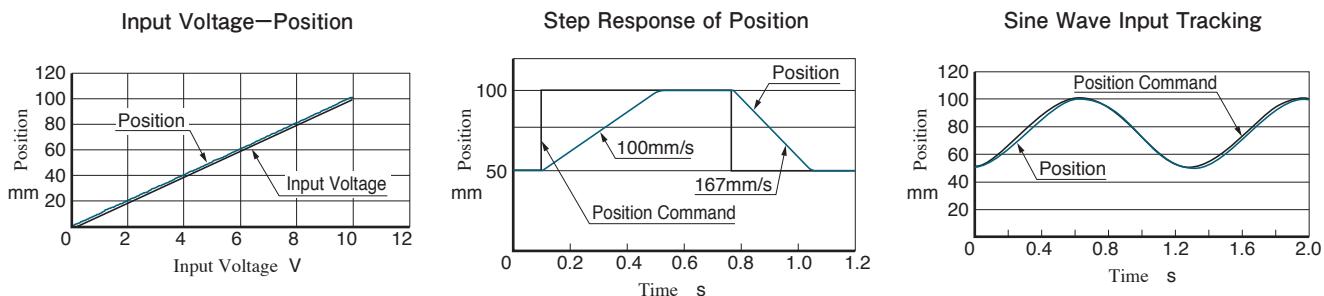
■ Example of Standard System Control

● Characteristics Example of The Position and Pressure Control System with IH Servo Drive Pack.

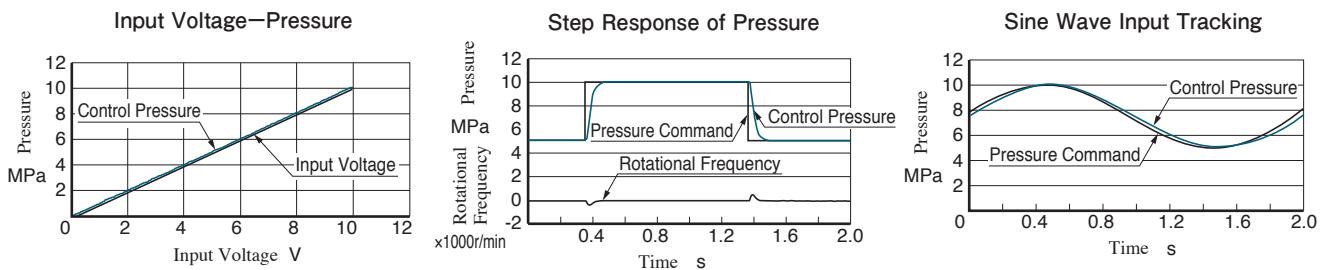
(Note: Control characteristics is different by system, please contact us separately.)

Structure Example : Cylinder 80 Dia. × 45 × 250st Use YSD2-F-44A44-16

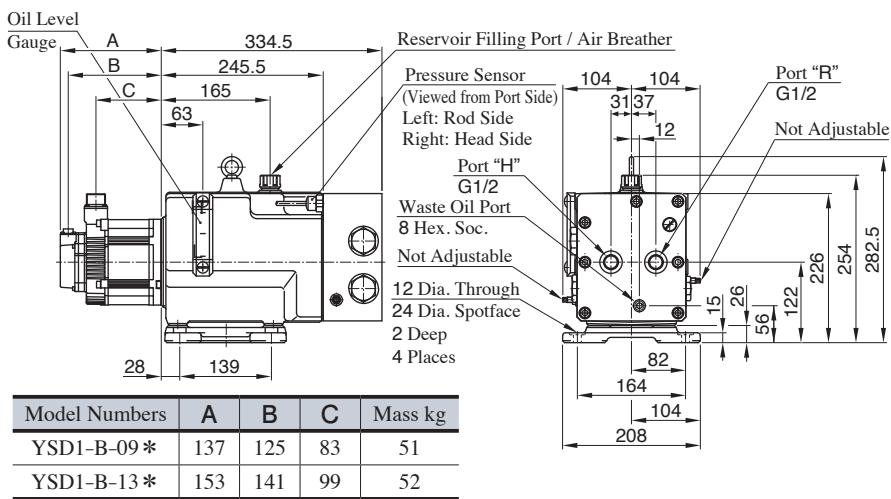
■ Characteristics Example of Position Control



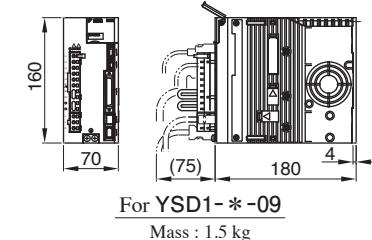
■ Characteristics Example of Pressure Control



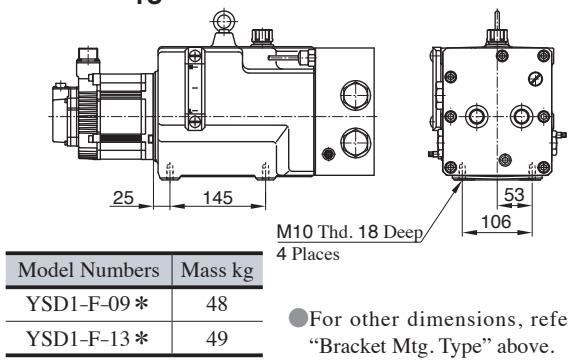
**YSD1-B-09
13 * * - * - * - * - 20 (Bracket Mtg. type)**



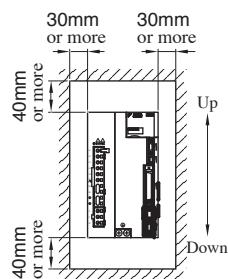
● Servo Pack



**YSD1-F-09
13 * * - * - * - * - 20 (Flange Mtg. type)**

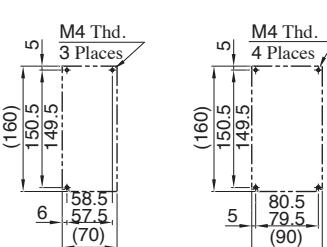


Mtg. Standard



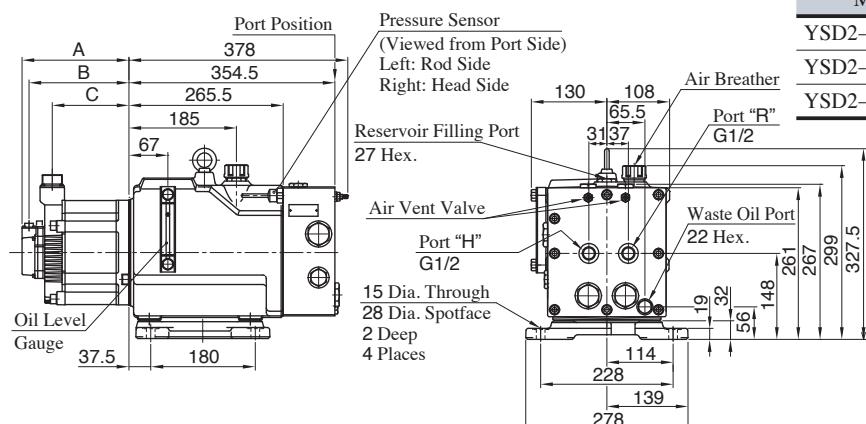
Dimension of Mtg. Hole

For YSD1-*09 For YSD1-*13



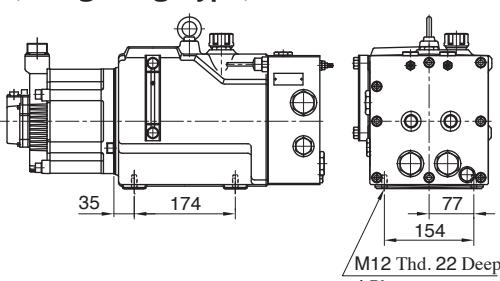
★ If set the servo amplifiers in a row, please contact us separately.

YSD2-B-*-*-*-*-*30 (Bracket Mtg. type)



Model Numbers	A	B	C	Mass kg
YSD2-B-24 *-*-*-*-*	160	148	108	84
YSD2-B-29 *-*-*-*-*				
YSD2-B-44 *-*-*-*-*	184	172	132	88

YSD2-F-*-*-*-*-*30 (Flange Mtg. type)

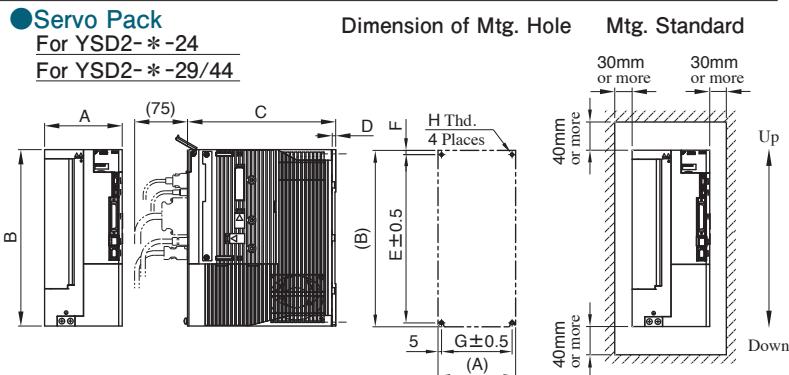


Model Numbers	Mass kg
YSD2-F-24 *-*-*-*-*	78
YSD2-F-29 *-*-*-*-*	
YSD2-F-44 *-*-*-*-*	82

● For other dimensions, refer to the "Bracket Mtg. Type" above.

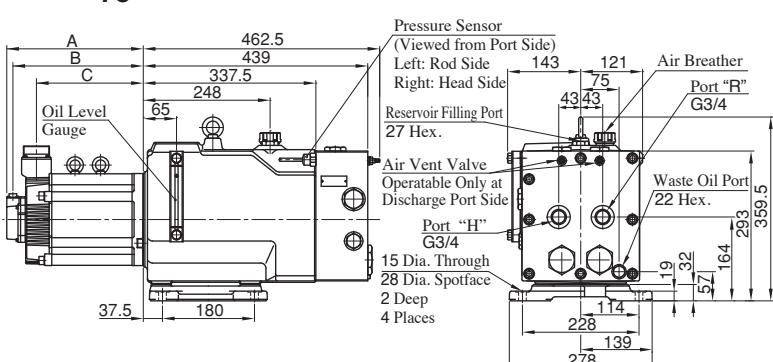
● Servo Pack

For YSD2-*24
For YSD2-*29/44



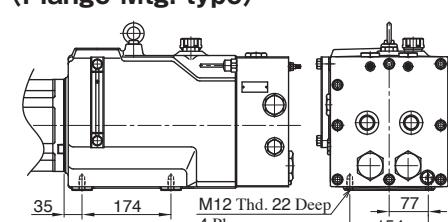
★ If set the servo amplifiers in a row, please contact us separately.

YSD3-B-55*-*-*-*-*30 (Bracket Mtg. type)



Model Numbers	A	B	C	Mass kg
YSD3-B-55 *-*-*-*-*	221	209	163	122
YSD3-B-75 *-*-*-*-*	267	255	209	130

YSD3-F-55*-*-*-*-*30 (Flange Mtg. type)

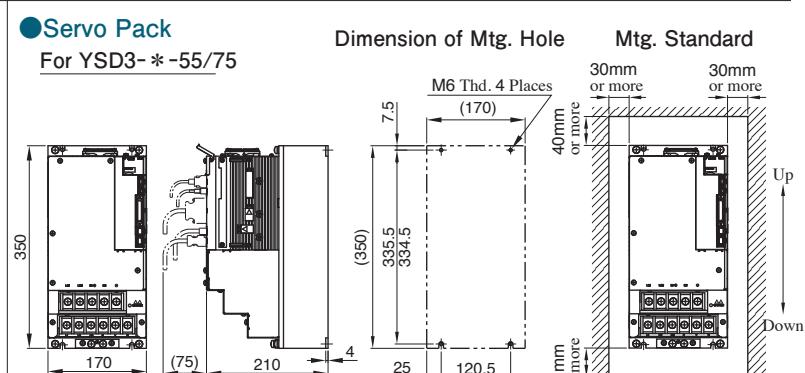


Model Numbers	Mass kg
YSD3-F-55 *-*-*-*-*	116
YSD3-F-75 *-*-*-*-*	124

● For other dimensions, refer to the "Bracket Mtg. Type" above.

● Servo Pack

For YSD3-*55/75



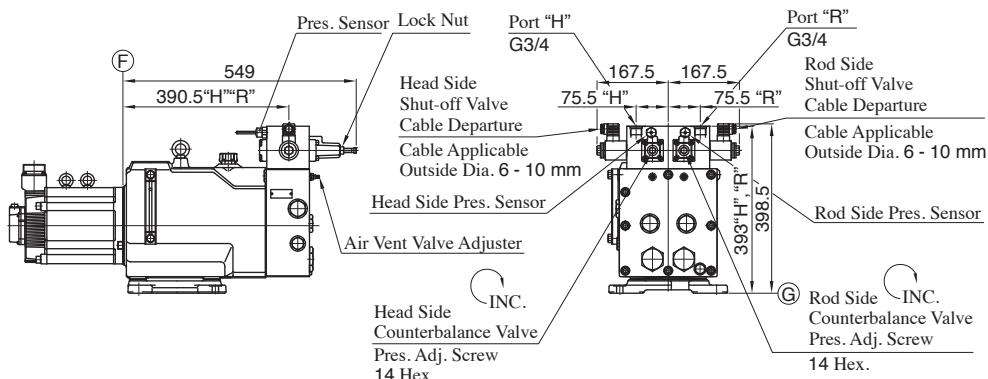
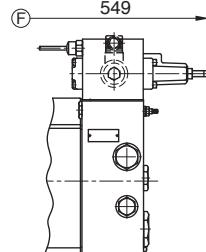
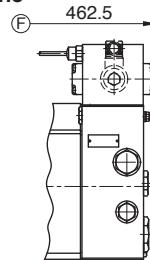
★ If set the servo amplifiers in a row, please contact us separately.

K

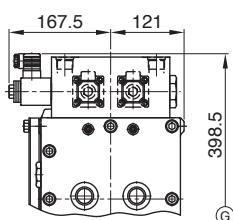
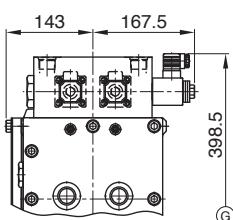
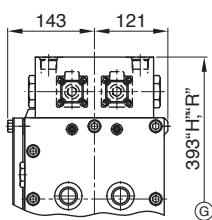
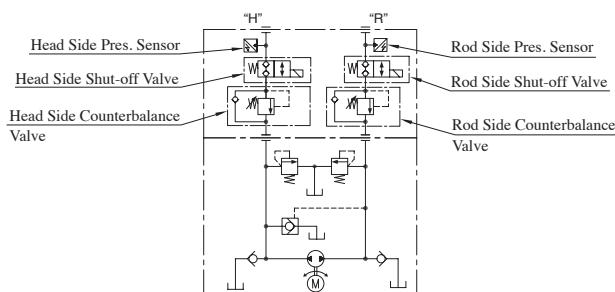
IH Servo Drive Pack

YSD3-*-**-BBB**

(Counterbalance Valves / Shut-off Valves : With Both Sides)

Options**Counterbalance Valves : With Head Side or Rod Side****Counterbalance Valves : None**

For other dimensions, refer to "Standard" on page K-65.

Shut-off Valves : With Head Side**Shut-off Valves : With Rod Side****Shut-off Valves : None****Graphic Symbol****Additional Mass with Options**

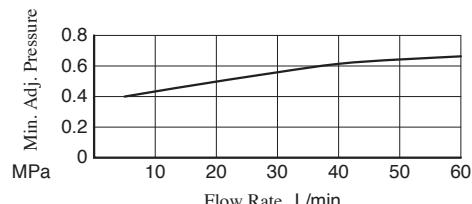
With options, add the additional mass below on that of "Standard" on page K-65.

Embedded Position of Option Valves		Additional Mass kg
Counterbalance Valves	Shut-off Valves	
Both Sides	Both Sides	16
	Head Side or Rod Side	
Head Side or Rod Side	Both Sides	
Combination Other Than The Above		15

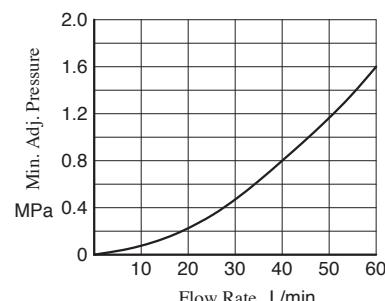
Specifications/Characteristics of Option Valves**Counterbalance Valves****Specifications**

Code of Pres. Adj. Range	Pres. Adj. Range MPa
N	★ - 1.8
A	1.8 - 3.5
B	3.5 - 7

★Please refer to the Min. Adj. Pressure below. If the model embedded with shut-off valves, that minimum adjustment pressure is the below value added pressure drop of shut-off valves.

Min. Adj. PressureViscosity 35 mm²/s Gravity 0.850**Shut-off Valves****Solenoid Ratings**

Power Supply	Voltage (V)		Current/Power at Power Supply Rated	
	Power Supply Rated	Range of Use	Holding Current (A)	Power (W)
DC	24	21.6 - 25.2	1.36	32.7

Pressure DropViscosity 35 mm²/s Gravity 0.850

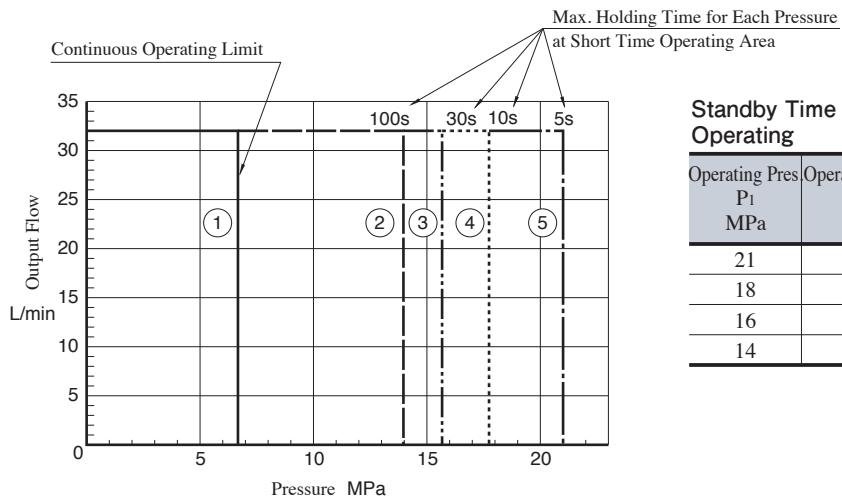
K

IH Servo Drive Pack

■ Pressure vs. Output Flow Characteristics

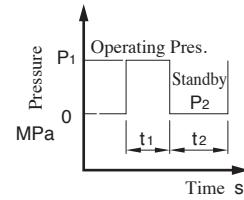
The characteristics charts below show the operating limits of "Pressure" and "Output Flow" calculated with AC servo motor specifications. For the characteristics charts, see the descriptions below.

● Description of Characteristics Chart



Standby Time after Short Time Operating

Operating Pres. P ₁ MPa	Operating time t ₁ s	Standby Time t ₂ s (P ₂ =0 MPa)
21	5	72
18	10	101
16	30	229
14	100	588

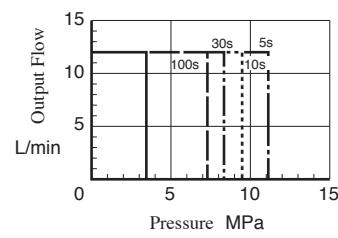


① Continuous Operating Area: The area can pressurizing continuously.

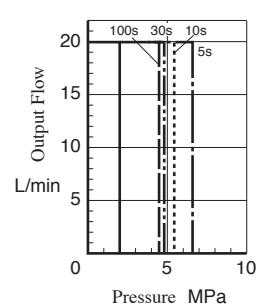
② - ⑤ Short Time Operating Area: The area can use only at the time limited on the characteristics chart. After operating, need a fixed standby time shown on the chart. The standby time on chart is the value at 0 MPa of the standby pressure. If the standby pressure higher than 0 MPa, the standby time is longer. For details, please contact us separately.

YSD1 Type

● YSD1-*09*09-6-*-*20



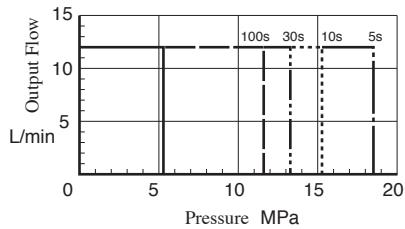
● YSD1-*09*09-10-*-*20



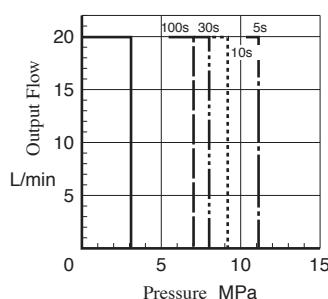
Standby Time after Short Time Operating

Operating Pres. P ₁ MPa	Operating time t ₁ s	Standby Time t ₂ s
6.6	5	86
5.4	10	105
4.9	30	238
4.3	100	607

● YSD1-*13*13-6-*-*20

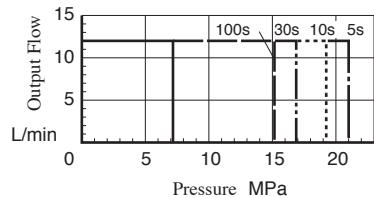


● YSD1-*13*13-10-*-*20



YSD2 Type

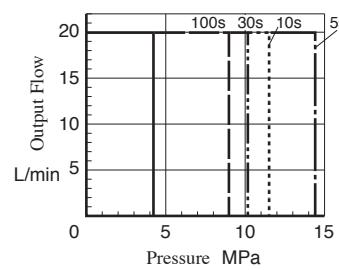
● YSD2- * -24 * 24-6- * * -30



Standby Time after Short Time Operating

Operating Pres. P ₁ MPa	Operating time t ₁ s	Standby Time t ₂ s
21	5	61
19	10	100
16.9	30	228
15	100	585

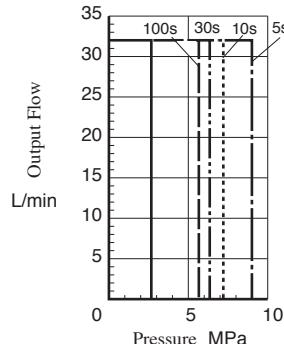
● YSD2- * -24 * 24-10- * * -30



Standby Time after Short Time Operating

Operating Pres. P ₁ MPa	Operating time t ₁ s	Standby Time t ₂ s
14	5	82
11.5	10	100
10	30	228
9	100	585

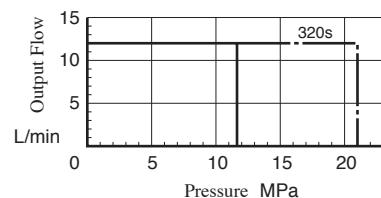
● YSD2- * -24 * 24-16- * * -30



Standby Time after Short Time Operating

Operating Pres. P ₁ MPa	Operating time t ₁ s	Standby Time t ₂ s
9	5	82
7	10	100
6	30	228
5.7	100	585

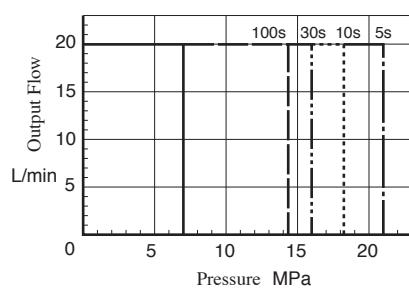
● YSD2- * -29 * 29-6- * * -30



Standby Time after Short Time Operating

Operating Pres. P ₁ MPa	Operating time t ₁ s	Standby Time t ₂ s
21	320	1294

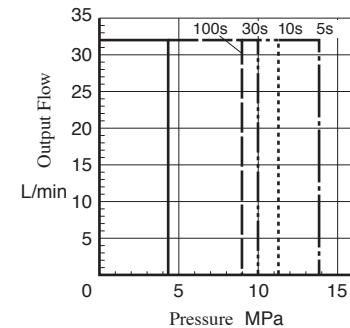
● YSD2- * -29 * 29-10- * * -30



Standby Time after Short Time Operating

Operating Pres. P ₁ MPa	Operating time t ₁ s	Standby Time t ₂ s
21	5	65
18	10	95
16	30	218
14	100	562

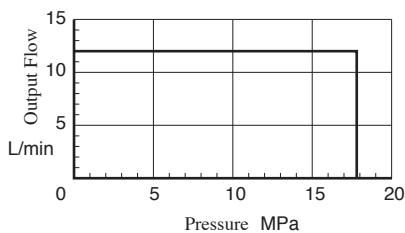
● YSD2- * -29 * 29-16- * * -30



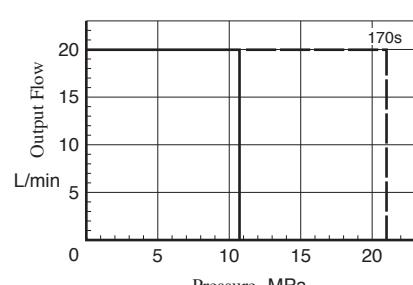
Standby Time after Short Time Operating

Operating Pres. P ₁ MPa	Operating time t ₁ s	Standby Time t ₂ s
13.9	5	77
11	10	95
10	30	218
9	100	562

● YSD2- * -44 * 44-6- * * -30



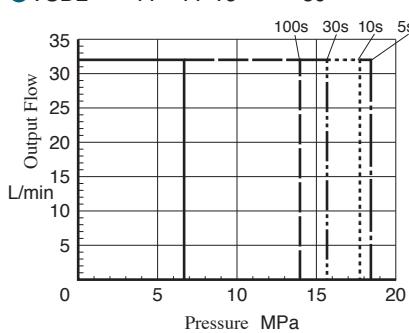
● YSD2- * -44 * 44-10- * * -30



Standby Time after Short Time Operating

Operating Pres. P ₁ MPa	Operating time t ₁ s	Standby Time t ₂ s
21	170	852

● YSD2- * -44 * 44-16- * * -30



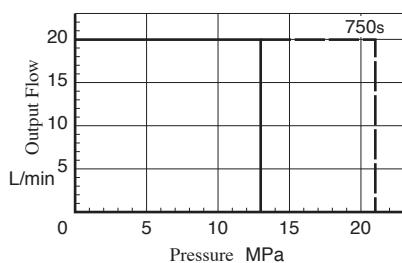
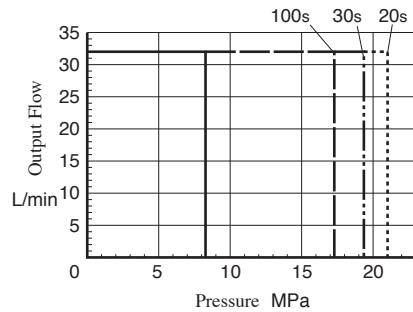
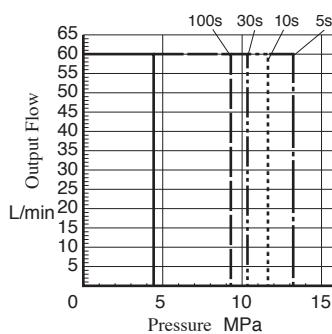
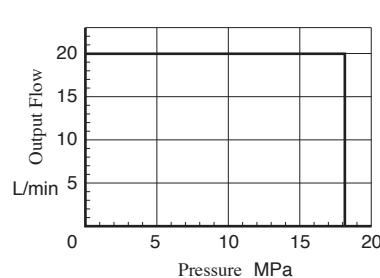
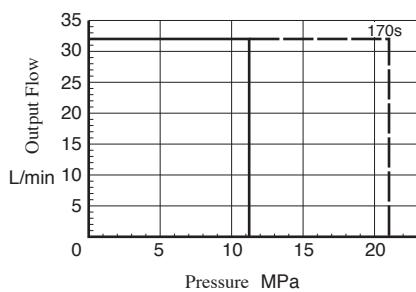
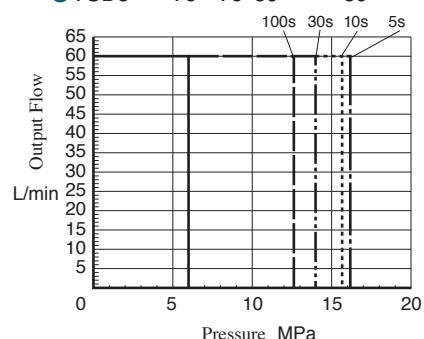
Standby Time after Short Time Operating

Operating Pres. P ₁ MPa	Operating time t ₁ s	Standby Time t ₂ s
18.3	5	72
17.8	10	101
15.7	30	229
14	100	588

★For the description of characteristics chart, refer to page K-68.

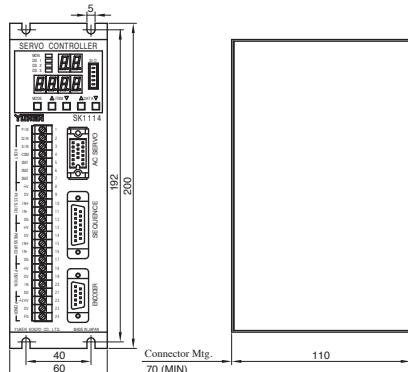
K

IH Servo Drive Pack

YSD3 Type
● YSD3- * -55 * 55-10- * * -30

● YSD3- * -55 * 55-16- * * -30

● YSD3- * -55 * 55-30- * * -30

● YSD3- * -75 * 75-10- * * -30

● YSD3- * -75 * 75-16- * * -30

● YSD3- * -75 * 75-30- * * -30


★ For the description of characteristics chart, refer to page K-68.

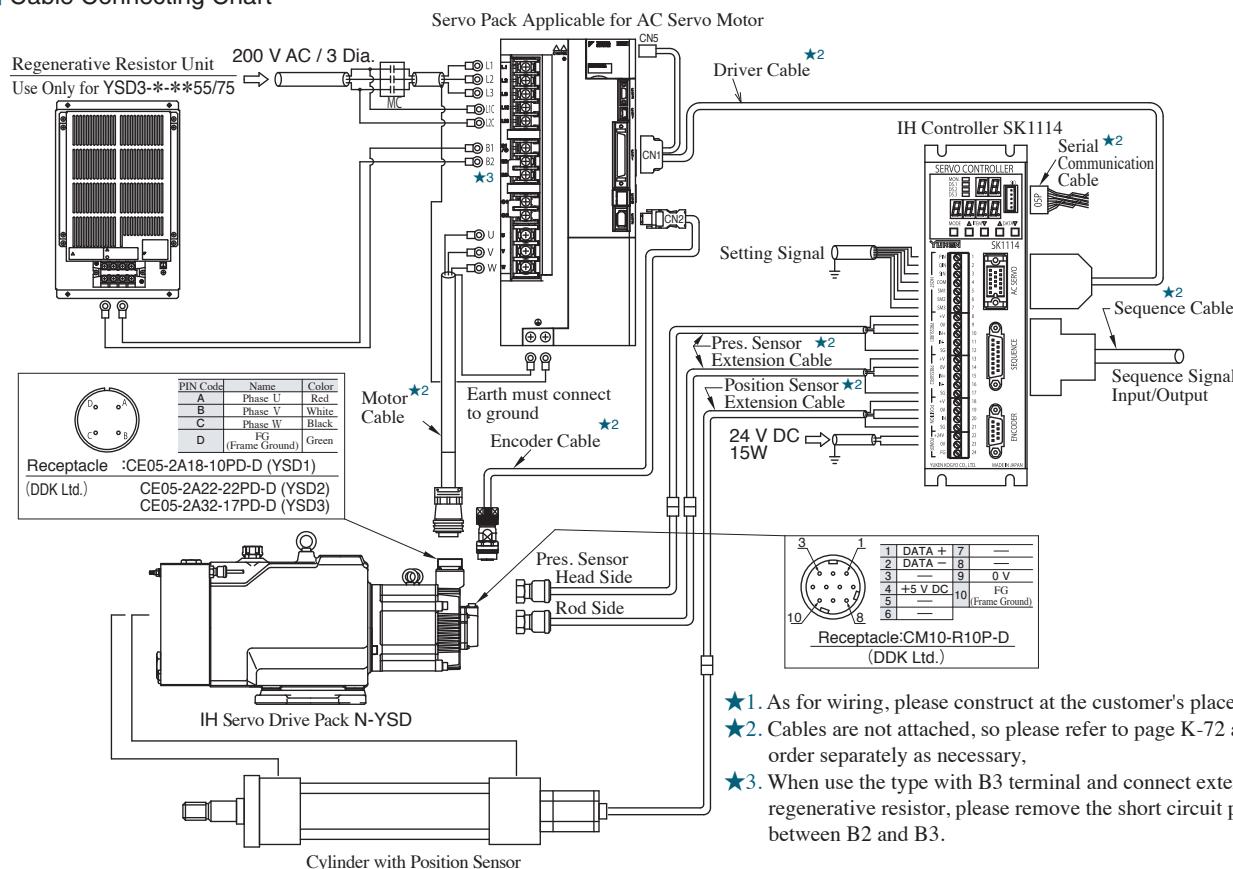
IH Controller : SK1114-11



Specifications

AC Servo Input	± 5 V
Input Impedance	10 k Ω (PIN, QIN, SIN)
Power Supply Voltage	24 V DC (21 - 28V Including Ripple)
Max. Power Consumption	10 W
Input Signal	Rated ± 5 V (PIN, QIN, SIN)
Signal for Sensor Monitor	± 5 V (SM*)
Ambient Temperature	0 - 50 °C
Mass	0.5 kg
ENCODER Input	Option

Cable Connecting Chart



Terminal Details

SK1114

Terminal Name	No.	Signal	Wire Color
HOST (Setting Signal Input/Output)	1 PIN	Pres. Input Signal	Red
	2 QIN	Flow Input Signal	White
	3 SIN	Position Input Signal	Blue
	4 COM	Signal Common	-
	5 SM1	General Monitor Output 1	Black
	6 SM2	General Monitor Output 2	Black
	7 SM3	General Monitor Output 3	Black
PRESSURE1 (Head Side Pres. Sensor)	8 +V	Sensor Power Supply	Red
	9 OV	(+4V)	White
	10 IN+	Sensor Input Signal	Green
	11 IN-	Sensor Input Signal	Blue
	12 SG	Shield Wire	-
PRESSURE2 (Head Side Pres. Sensor)	13 +V	Sensor Power Supply	Red
	14 OV	(+4V)	White
	15 IN+	Sensor Input Signal	Green
	16 IN-	Sensor Input Signal	Blue
	17 SG	Shield Wire	-
POSITION (Position Sensor)	18 +V	Sensor Power Supply	Brown
	19 OV	(+24V)	Blue/Grey
	20 IN	Sensor Input Signal	Green
	21 SG	Shield Wire	-
POWER (Power Supply)	22 +24V	+24[V]	-
	23 OV	0[V]	-
	24 FG	Ground	-

Connector Details

AC SERVO
(Driver Cable Connect)

No.	Signal	Wire Color
1 PIN	Pres. Input Signal	Red
2 QIN	Flow Input Signal	White
3 SIN	Position Input Signal	Blue
4 COM	Signal Common	-
5 SM1	General Monitor Output 1	Black
6 SM2	General Monitor Output 2	Black
7 SM3	General Monitor Output 3	Black
8 +V	Sensor Power Supply	Red
9 OV	(+4V)	White
10 IN+	Sensor Input Signal	Green
11 IN-	Sensor Input Signal	Blue
12 SG	Shield Wire	-
13 +V	Sensor Power Supply	Red
14 OV	(+4V)	White
15 IN+	Sensor Input Signal	Green
16 IN-	Sensor Input Signal	Blue
17 SG	Shield Wire	-
18 +V	Sensor Power Supply	Brown
19 OV	(+24V)	Blue/Grey
20 IN	Sensor Input Signal	Green
21 SG	Shield Wire	-
22 +24V	+24[V]	-
23 OV	0[V]	-
24 FG	Ground	-

SIO
(Serial Communication Cable Connect)

No.	Signal
1 TxD	Send Data Output
2 RxD	Receive Data Input
3 RTS	Send Ready Output
4 CTS	Send Ready Input
5 GND	Common

Upper Communication : RS-232C

SEQUENCE
(Sequence Cable Connect)

No.	Signal
1 COM	Input Common
2 IN1	Code Input (BIN)
3 IN2	x0 - x7
4 IN3	-
5 IN4	Select Control Mode
6 IN5	Select Control Direction
7 IN6	Standby
8 IN7	Alarm Reset
9 IN8	Servo ON
10 OUT1	Code Change Recognition
11 OUT2	Standby
12 OUT3	Coincidence
13 OUT4	Alarm
14 COM	Output Common
15 Unused	-

Cable Connector and Wire

Housing	Sequence Cable	Driver Cable	Serial Communication Cable
DA-15P (JAE)	DA-15P (JAE)	MR-16M (HONDA)	XHP-5 (JST)
Case	DA-C4-J10 (JAE)	MR-16L (HONDA)	SXH-001T-P0.6 (JST)
Core Wire Size	AWG # 20	AWG # 24 - 28	AWG # 22 - 28
Coated Outside Dia.	2.9 Dia.	1.2 - 1.5 Dia.	0.9 - 1.9 Dia.
Strip Length	2.0 - 2.5mm	2.0 - 2.5mm	1.2 - 2.6mm

Pressure Sensor

Model	KH17 (NAGANO KEIKI)
Range	0 - 35MPa
Output	70±25mV DC
Operating Voltage	5V DC
Precision	±0.5 % F.S.
Power Supply (-)	Standard Cable Length 2m

Position Sensor

Model	BTLS-A11-*(BALLUFF)
Standard Cable Length	5m

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IH Servo Drive Pack

■ Cables

Cables are not attached for IH servo drive pack, so please refer to the table below and order separately as necessary.
The cables except for motor cable are common to each model.

● Motor Cable

IH Servo Drive Pack Model Numbers	Cable Model Numbers	Notes
YSD1-* -09 * -	YSDC-M1-09-☆-★-10	
YSD1-* -13 * -	YSDC-M1-13-☆-★-10	
YSD2-* -24 * -	YSDC-M1-29-☆-★-10	
YSD2-* -29 * -	YSDC-M1-29-☆-★-10	
YSD2-* -44 * -	YSDC-M1-44-☆-★-10	
YSD3-* -55 * -	YSDC-M1-55-☆-★-10	
YSD3-* -75 * -	YSDC-M1-75-☆-★-10	

☆ : Plug Type
S : Straight Type L : L Type
★ : Cable Length
03 : 3m 05 : 5m 10 : 10m 15 : 15m 20 : 20m
N : Plug and Cable Clamp Only

● Sequence Cable / Driver Cable

Cable Type	Cable Model Numbers	Notes
Sequence Cable	YSDC-S1-00-★-10	★ : Cable Length 03 : 3m 05 : 5m 10 : 10m 15 : 15m 20 : 20m
Driver Cable	YSDC-D1-★-10	★ : Cable Length 01 : 1m 02 : 2m 03 : 3m

● Encoder Cable / Pres. Sensor Extension Cable / Position Sensor Extension Cable

Cable Type	Cable Model Numbers	Notes
Encoder Cable	YSDC-E8-☆-★-10	☆ : Plug Type S : Straight Type L : L Type ★ : Cable Length R03 : 0.3m 03 : 3m 05 : 5m 10 : 10m 15 : 15m 20 : 20m
Pres. Sensor Extension Cable	YSDC-P1-01-★-10	★ : Cable Length 03 : 3m 05 : 5m 10 : 10m 15 : 15m 20 : 20m 50 : 50m
Position Sensor Extension Cable	YSDC-L1-01-★-10	★ : Cable Length 03 : 3m 05 : 5m 10 : 10m 15 : 15m 20 : 20m

● Serial Communication Cable

Cable Type	Cable Model Numbers	Notes
Serial Communication Cable	YSDC-T2-☆-★-10	☆ : Cable End Type 02 : Dsub-9pin ★ : Cable Length 03 : 3m 05 : 5m 10 : 10m

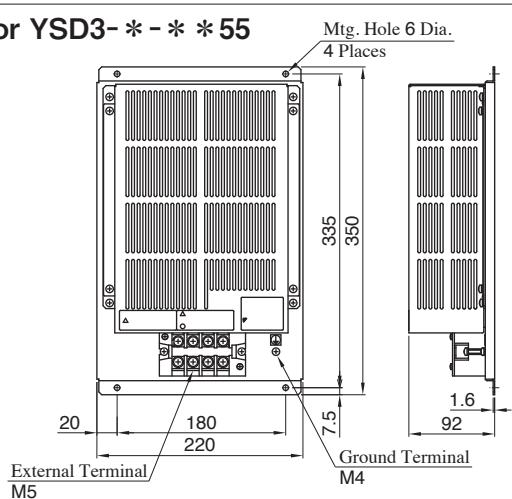
■ Regenerative Resistor Unit

● Specifications

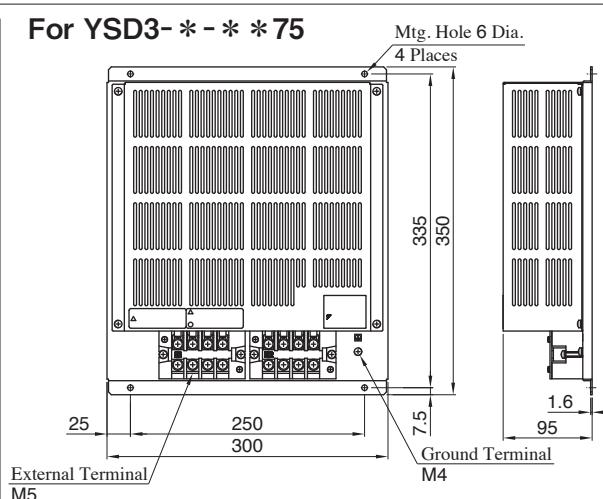
IH Servo Drive Pack Model Numbers	YASKAWA ELECTRIC Model	Resistance Value	Power	Approx. Mass kg
YSD3-* - * * 55-	JUSP-RA04-E	6.25Ω (25Ω×4Parallel Connected)	880W (220W×4)	4.2
YSD3-* - * * 75-	JUSP-RA05-E	3.13Ω (25Ω×8Parallel Connected)	1760W (220W×8)	6.6

★Regenerative resistor may reach to high temperature. Please use heat-resistant fireproof wires and avoid to contact the regenerative resistor on wiring.

For YSD3- * - * * 55



For YSD3- * - * * 75



■ Interchangeability between Current and New Models

Because the motor manufacturer stopped production of the built-in servo motor, so IH servo drive pack has changed models as below.

● Major Changes

- ①Totally Change of Servo Motor and Servo Pack.
- ②1.8 kW embedded model changes to 2.4 kW embedded model same as above.
- ③Change The Connector Type of Encoder Cable.

● Design Number

Series	Change of Design Number
YSD1	10→20 Design
YSD2/YSD3	20→30 Design

● Interchangeability in Installation

There is interchangeability between current and new pumps with no changes.

As for servo motor, servo pack and encoder cable, there is no interchangeability between current and new models, so these parts of current design have to exchange as a set.

Interchangeability	Name	No Interchangeability / Differences	No Interchangeability / Details
Yes	Pump	—	—
No	Servo Motor	Distance from Pump Mtg. Surface to Cable Connecting Position	Page K-74
No	Servo Pack	Mtg. Hole Dimensions Connector Insert Direction for YSD3	Page K-75
Yes	Motor Cable Sequence Cable Driver Cable Pres. Sensor Extension Cable Position Sensor Extension Cable	—	—
No	Serial Communication Cable	Cable End Type : Delete Some Parts	Page K-76
No	Encoder Cable	Cable Length, Connector type	Pages K-73, K-75
Yes*	Regenerative Resistor Unit	—	—

*The model numbers are changed (see the table below).

● Model Numbers

①IH Servo Drive Pack

Current Model Numbers	New Model Numbers
YSD2-* -18A18-*-*-*-*-* -20	YSD2-* -24A24-*-*-*-*-* -30

②Encoder Cable / Regenerative Resistor Unit

Current Model Numbers		New Model Numbers	
Encoder Cable	Regenerative Resistor Unit	Encoder Cable	Regenerative Resistor Unit
YSDC-E1-★-★-10 ★ : Cable Length 03 : 3m 05 : 5m 10 : 10m 15 : 15m 20 : 20m 50 : 50m	JUSP-RA04	YSDC-E8-★-★-10 ★ : Cable Length R3 : 0.3m 03 : 3m 05 : 5m 10 : 10m 15 : 15m 20 : 20m	JUSP-RA04-E
	JUSP-RA05		JUSP-RA05-E

● Specifications

Current and new models are same except below.

1. Servo Motor Output / Servo Pack type

Current			New		
Model Numbers	Servo Motor Output	Servo Pack type	Model Numbers	Servo Motor Output	Servo Pack type
YSD2-*18A18	1.8 kW	For 1.8 kW Motor	YSD2-*24A24	2.4 kW	For 2.4 kW Motor

2. Mass

① Pump / Motor

Current			New		
Model Numbers	Mass Flange Mtg. Type	Mass Foot Mtg. Type	Model Numbers	Mass Flange Mtg. Type	Mass Foot Mtg. Type
YSD1-*09A09-*-*-*10	50 kg	53 kg	YSD1-*09A09-*-*-*20	48 kg	51 kg
YSD1-*13A13-*-*-*10	52 kg	55 kg	YSD1-*13A13-*-*-*20	49 kg	52 kg
YSD2-*29A29-*-*-*20	82 kg	88 kg	YSD2-*29A29-*-*-*30	78 kg	84 kg
YSD2-*44A44-*-*-*20	87 kg	93 kg	YSD2-*44A44-*-*-*30	82 kg	88 kg
YSD3-*55A55-*-*-*20	124 kg	130 kg	YSD3-*55A55-*-*-*30	116 kg	122 kg
YSD3-*75A75-*-*-*20	134 kg	140 kg	YSD3-*75A75-*-*-*30	124 kg	130 kg

② Servo Pack

Current		New	
Type	Mass	Type	Mass
For YSD1-*09	1.7 kg	For YSD1-*09	1.5 kg
For YSD1-*13	2.8 kg	For YSD1-*13	2.4 kg
For YSD2-*18/29	3.8 kg	For YSD2-*24	2.8 kg
For YSD2-*44	5.5 kg	For YSD2-*29/44	4.6 kg
For YSD3-*55/75	14.6 kg	For YSD3-*55/75	10.2 kg

● Characteristics

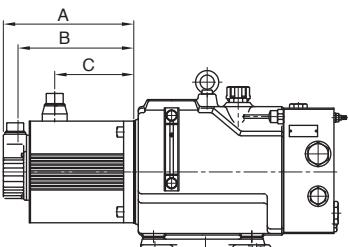
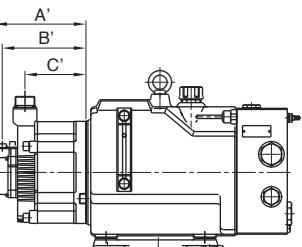
Pressure vs. Output Flow Characteristics are changed as below.

- ① Operating pressure at short time operating is changed a part.
- ② Delete the forced air cooling area at continuous and short time operating.

● Dimensions

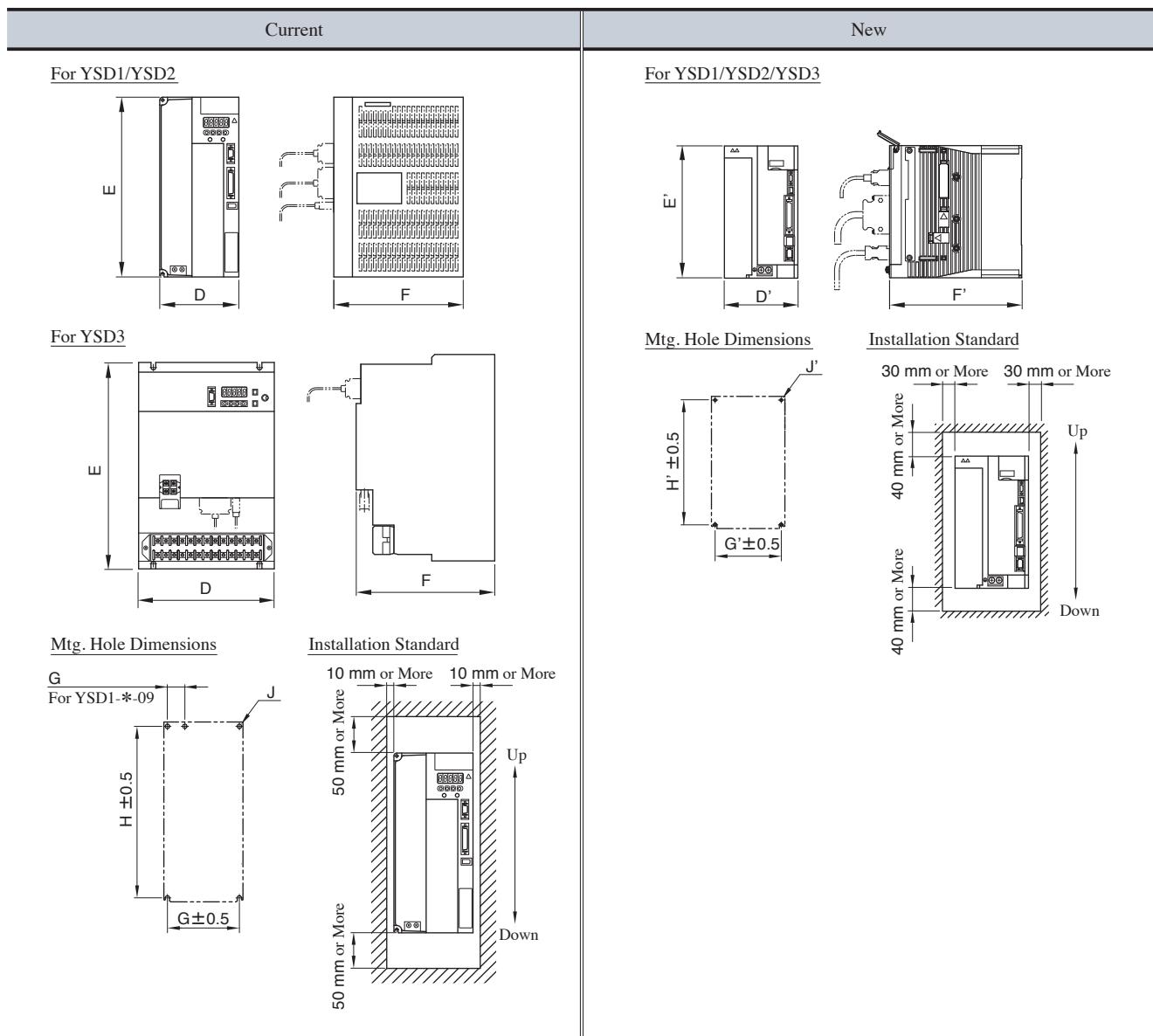
① Pump / Mootor

Current			New				
Model Numbers	A	B	C	Model Numbers	A'	B'	C'
YSD1-*09A09-*-*-*10	161	140	88	YSD1-*09A09-*-*-*20	137	125	83
YSD1-*13A13-*-*-*10	185	164	112	YSD1-*13A13-*-*-*20	153	141	99
YSD2-*18A18-*-*-*20	166	144	89	YSD2-*24A24-*-*-*30	160	148	108
YSD2-*29A29-*-*-*20	192	170	115	YSD2-*29A29-*-*-*30	160	148	108
YSD2-*44A44-*-*-*20	226	204	149	YSD2-*44A44-*-*-*30	184	172	132
YSD3-*55A55-*-*-*20	260	238	174	YSD3-*55A55-*-*-*30	221	209	163
YSD3-*75A75-*-*-*20	334	312	248	YSD3-*75A75-*-*-*30	267	255	209

Current			New		
					

②Servo Pack

Type	Current						Type	New					
	D	E	F	G	H	J		D'	E'	F'	G'	H'	J'
For YSD1-* -09	90	160	180	27	149.5	5	For YSD1-* -09	70	160	180	58	150	(5)
For YSD1-* -13	110	160	180	100	149.5	5	For YSD1-* -13	90	160	180	80	150	(5)
For YSD2-* -18/29	110	250	180	100	238.5	6	For YSD2-* -24	100	180	180	90	170	(5)
For YSD2-* -44	135	250	230	125	238.5	5.7	For YSD2-* -29/44	110	250	210	100	238.5	(6)
For YSD3-* -55/75	230	350	235	180	335	7	For YSD3-* -55/75	170	350	210	120	335	(7)



③Encoder Cable

Current				New			
PIN Code	Name	PIN Code	Name	PIN Code	Name	PIN Code	Name
A	—	K	—	1	DATA +	1	DATA +
B	—	L	—	2	DATA -	2	DATA -
C	DATA +	M	—	3	—	3	—
D	DATA -	N	—	4	+5 V DC	4	+5 V DC
E	—	P	—	5	—	5	—
F	—	R	—	6	—	6	—
G	0 V	S	—	7	—	7	—
H	+ 5 V DC	T	—	8	—	8	—
J	FG (Frame Ground)			9	0 V	9	0 V
				10	FG (Frame Ground)	10	FG (Frame Ground)

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IH Servo Drive Pack

④Serial Communication Cable

Descriptions	Current	New
Cable Model Numbers	YSDC-T1-☆-★-10	YSDC-T2-☆-★-10
Cable End Type	01 : Dsub-25pin 02 : Dsub-9pin	02 : Dsub-9pin

■ Solenoid Ratings

Type	Power Supply	Coil Type ^{★3}	Frequency (Hz)	Voltage (V)		Current/Power at Rated Power Supply Voltage		
				Power Supply Rated	Range of Use	Inrush Current ^{★2} (A)	Holding Current (A)	Power (W)
Standard Type	AC ^{★1}	A 100	50	100	80 - 110	2.42	0.51	
			60	100	90 - 120	2.14	0.37	
				110		2.35	0.44	
		A 120	50	120	96 - 132	2.02	0.42	
			60		108 - 144	1.78	0.31	
		A 200	50	200	160 - 220	1.21	0.25	
			60	200	180 - 240	1.07	0.19	
				220		1.18	0.22	
		A 240	50	240	192 - 264	1.01	0.21	
			60		216 - 288	0.89	0.15	
Shockless Type	DC (K Series)	D 12	—	12	10.8 - 13.2	—	2.45	
		D 24		24	21.6 - 26.4		1.23	29
		D 48		48	43.2 - 52.8		0.61	
	R (AC→DC)	R 100	50/60	100	90 - 110	—	0.33	29
		R 200		200	180 - 220		0.16	

★1. AC Solenoid

AC Solenoid (A *) is not available for the shockless type. If need shockless type of power supply, please order R type solenoid (R *).

★2. Inrush Current

The inrush current value indicates the rms value at max. stroke.

★3. The coil types other than the above are also available. For details, please contact us separately.

The coil types highlighted with shade represent the optional extras. If use, please confirm the time of delivery with us before ordering.